



**CALIFORNIA STATE SCIENCE FAIR  
2011 PROJECT SUMMARY**

<b>Name(s)</b> <b>Jedediah A. Fitzgerald</b>	<b>Project Number</b>  31217
<b>Project Title</b> <b>We're Ready or Liftoff: Examining the Effects of Hovering Heights on Produced RPM's</b>	
<p style="text-align: center;"><b>Abstract</b></p> <p><b>Objectives/Goals</b> My goal for my project is to determine at which hovering height, over which terrain will a helicopter produce the least amount of RPM's.</p> <p><b>Methods/Materials</b> For my experiment I used one (1) Craftsman tape measurer, one (1) Blade XC2 Helicopter, one (1) Blade XC2 remote control, one (1) stroboscope, a 35x25 square of river rock, a 35x25 square of asphalt, and a 35x25 square of grass. I hovered the helicopter at the variable height, over the designated terrain, taking measurements with the stroboscope and recording my results.</p> <p><b>Results</b> My results showed that, on average, the .609 meter hover over grass produced the least amount of RPM's, the 1.22 meter hover over asphalt produced a middle amount, and the 1.83 meter hover over river rock produced the most RPM's.</p> <p><b>Conclusions/Discussion</b> In conclusion, I discovered that to lessen the amount of RPM's produced, you should fly your helicopter low over smooth, level surfaces such as asphalt or grass.</p>	
<b>Summary Statement</b> I chose this project because I wanted to lessen the amount of RPM's produced by a helicopter in order to save fuel.	
<b>Help Received</b> My mother took readings with the stroboscope, Carrie Given and Mrs. Lopez-Lickey, science teachers, helped with papers.	